

# Analysis of a model for adhesive contact with thermal effects

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**joint work with**

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## Frémond's modeling of adhesive contact

### Setting

A viscoelastic body  $\Omega \subset \mathbb{R}^3$  in **adhesive contact** with a rigid support on a **(flat)** part  $\Gamma_{\text{Cont}}$  of its boundary  $\partial\Omega = \Gamma_{\text{Dir}} \cup \Gamma_{\text{Neu}} \cup \Gamma_{\text{Cont}}$ .

### Related contributions

.... Andrews, Cangémi, Chau, Cocou, Eck, Fernández, Figuereido, Han, Jarušek, Klarbring, Krbec, Kuttler, Martins, Muñoz-Rivera, Point, Racke, Raous, Shi, Shillor, Sofonea, Telega, Trabucho, Wright.....

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Based on [M. Frémond, *Non-smooth Thermomechanics*, 2002]

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### Frémond's approach

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Account for **microscopic motions** in the **macroscopic predictive theory**

- ▶ microscopic bonds are responsible for the adhesion, microscopic motions lead to rupture
- ▶ account for the **power of the microscopic motions** in the power of the interior forces

## State variables

In the **isothermal case** [Bonetti-Bonfanti-R. '07,'08]

- ▶ in the **volume domain**  $\Omega$ :
  - ▶ **small deformation** ( $\varepsilon(\mathbf{u})$  symm. linear. strain tensor) (**small perturbation assumption**)
  - ▶
- ▶ on the **contact surface**  $\Gamma_{\text{Cont}}$ :
  - ▶ **adhesion** ( $\chi$  “phase parameter” related to the active bonds of the adhesion  $\rightsquigarrow$  “damage parameter”)
  - ▶ **effects of displacement** ( $\mathbf{u}|_{\Gamma_{\text{Cont}}}$  trace of the displacement)
  - ▶

## State variables

To account for **thermal effects**: [Bonetti-Bonfanti-R. preprint'08]

- ▶ in the **volume domain**  $\Omega$ :
  - ▶ **small deformation** ( $\varepsilon(\mathbf{u})$  symm. linear. strain tensor) (**small perturbation assumption**)
  - ▶ **thermal effects** ( $\theta$  absolute temperature)
  
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  - ▶ **thermal effects** ( $\theta_s$  absolute temperature)

## The equations for $\mathbf{u}$ and $\chi$

From the **principle of virtual power** (interior & exterior forces, no acceleration forces)

► **momentum balance:**

$$\left\{ \begin{array}{l} -\operatorname{div} \Sigma = \mathbf{f} \quad \text{in } \Omega \times (0, T), \\ \left\{ \begin{array}{l} \Sigma \mathbf{n} = \mathbf{R} \quad \text{in } \Gamma_{\text{Cont}} \times (0, T), \\ \mathbf{u} = \mathbf{0} \quad \text{in } \Gamma_{\text{Dir}} \times (0, T), \\ \Sigma \mathbf{n} = \mathbf{g} \quad \text{in } \Gamma_{\text{Neu}} \times (0, T), \end{array} \right. \end{array} \right.$$

$$\left\{ \begin{array}{l} \Sigma \text{ stress tensor} \\ \mathbf{R} \text{ reaction on the contact surface} \\ \mathbf{f} \text{ volume force, } \mathbf{g} \text{ traction} \end{array} \right.$$

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► **equation for the microscopic motions:**

$$\left\{ \begin{array}{l} B - \operatorname{div} \mathbf{H} = 0 \quad \text{in } \Gamma_{\text{Cont}} \times (0, T), \\ \mathbf{H} \cdot \mathbf{n}_s = 0 \quad \text{on } \partial \Gamma_{\text{Cont}} \times (0, T), \end{array} \right.$$

$$\left\{ \begin{array}{l} B \text{ interior microscopic work} \\ \mathbf{H} \text{ microscopic work flux vector} \end{array} \right.$$

## The equations for $\theta$ and $\theta_s$

**Entropy balance** for  $\theta$  and  $\theta_s$ :

► for  $\theta$ :

$$\begin{cases} s_t + \operatorname{div} \mathbf{Q} = h & \text{in } \Omega \times (0, T), \\ \mathbf{Q} \cdot \mathbf{n} = F & \text{on } \Gamma_{\text{Cont}} \times (0, T), \\ \mathbf{Q} \cdot \mathbf{n} = 0 & \text{on } \partial\Omega \setminus \Gamma_{\text{Cont}} \times (0, T), \end{cases}$$

$$\begin{cases} s & \text{internal entropy} \\ \mathbf{Q} & \text{entropy flux vector} \\ h & \text{entropy source,} \\ F & \text{entropy flux through } \Gamma_{\text{Cont}} \end{cases}$$

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▶ for  $\theta_s$  :

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**Entropy balance:** obtained by rescaling the internal energy balance (under small perturbation assumpt.): see [\[Bonetti-Frémond'03, Bonetti-Colli-Frémond'03, Bonetti'06, Bonetti-Colli-Fabrizio-Gilardi'06,'07,08, Bonetti-Rocca-Frémond'07\]](#)

## Constitutive laws

Constitutive relations for

$$\Sigma, \mathbf{R}, s, \mathbf{Q}, F, B, \mathbf{H}, s_s, \mathbf{Q}_s$$

derive from the **volume & surface free energies**

$$\Psi_\Omega = \Psi_\Omega(\mathbf{u}, \theta), \quad \Psi_{\Gamma_{\text{Cont}}} = \Psi_{\Gamma_{\text{Cont}}}(\mathbf{u}|_{\Gamma_{\text{Cont}}}, \chi, \theta_s)$$

and the **pseudo-potentials of dissipation**

$$\Phi_\Omega = \Phi_\Omega(\nabla\theta, \varepsilon(\mathbf{u}_t)), \quad \Phi_{\Gamma_{\text{Cont}}} = \Phi_{\Gamma_{\text{Cont}}}(\nabla\theta_s, \chi_t, \theta|_{\Gamma_{\text{Cont}}} - \theta_s)$$

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The energy potentials include **constraints on the variables** for physical consistency:  $\rightsquigarrow$  **nonsmooth (multivalued) operators** in the constitutive eqns

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## Constraints

- ▶ admissible values for  $\chi$  and (possibly) irreversibility
- ▶ impenetrability condition between the body and the support
- ▶ positivity of the absolute temperatures  $\theta$  and  $\theta_s$

## The adhesion phenomenon

The “damage parameter”  $\chi$  denotes the **fraction of active glue fibers** at each point of the contact surface

- ▶  $\chi = 0$  no adhesion (completely broken bonds)
- ▶  $\chi = 1$  active adhesion (unbroken bonds)

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### Physical constraints

- ▶  $\chi \in [0, 1]$
- ▶  $\chi_t \leq 0$  (irreversible phenomenon)

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As a first step, neglect irreversibility ( $\sim$  fresh, liquid glue..)

## Unilateral conditions

The **impenetrability condition**

$$\mathbf{u}|_{\Gamma_{\text{Cont}}} \cdot \mathbf{n} \leq 0 \quad \text{on } \Gamma_{\text{Cont}}.$$

is ensured by the reaction on the contact surface

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If  $\chi = 0$  (no adhesion) the reaction on  $\Gamma_{\text{Cont}}$  is

$$\mathbf{R} = -\partial l_{[-\infty, 0]}(\mathbf{u} \cdot \mathbf{n})\mathbf{n}$$

(omitting traces) where

$$\partial l_{[-\infty, 0]}(\mathbf{u} \cdot \mathbf{n}) = \begin{cases} 0 & \text{if } \mathbf{u} \cdot \mathbf{n} < 0 \\ [0, +\infty[ & \text{if } \mathbf{u} \cdot \mathbf{n} = 0 \end{cases}$$

- ▶  $\mathbf{R}$  is normal to  $\Gamma_{\text{Cont}}$
- ▶  $\mathbf{R} = \mathbf{0}$  if  $\mathbf{u} \cdot \mathbf{n} < 0$
- ▶  $\mathbf{R} = \gamma\mathbf{n}$ ,  $\gamma \leq 0$  if  $\mathbf{u} \cdot \mathbf{n} = 0$

This is in agreement with the **Signorini conditions**

## Unilateral conditions

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is ensured by the reaction on the contact surface

In the case the adhesion is active  $\chi > 0$

$$\mathbf{R} = -\chi \mathbf{u} - \partial \mathbf{l}_{]-\infty, 0]}(\mathbf{u} \cdot \mathbf{n}) \mathbf{n}$$

i.e., there is a reaction (with rigidity  $\sim \chi$ ) **counteracting separation:**

$$\mathbf{R} \cdot \mathbf{n} = -\chi \mathbf{u} \cdot \mathbf{n} > 0 \text{ if } \mathbf{u} \cdot \mathbf{n} < 0$$

## The PDE system: the momentum balance

Recall  $\Omega \subset \mathbb{R}^3$  smooth, bounded and  $\partial\Omega = \Gamma_{\text{Dir}} \cup \Gamma_{\text{Neu}} \cup \Gamma_{\text{Cont}}$

- ▶ The momentum balance

$$-\operatorname{div} (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1}) = \mathbf{f} \quad \text{in } \Omega \times (0, T)$$

where:  $K$  elasticity tensor,  $K_v$  viscosity tensor,  $\theta\mathbf{1} \leftrightarrow$  **thermal deformation**

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- ▶ the **boundary conditions**

$$\mathbf{u} = \mathbf{0} \quad \text{on } \Gamma_{\text{Dir}}, \quad (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1})\mathbf{n} = \mathbf{g} \quad \text{on } \Gamma_{\text{Neu}} \times (0, T),$$

$$(K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1})\mathbf{n} + \chi\mathbf{u} + \partial h_{-\infty,0] }(\mathbf{u} \cdot \mathbf{n})\mathbf{n} \ni \mathbf{0} \quad \text{on } \Gamma_{\text{Cont}} \times (0, T),$$

where  $-\chi\mathbf{u} - \partial h_{-\infty,0] }(\mathbf{u} \cdot \mathbf{n})\mathbf{n}$  on  $\Gamma_{\text{Cont}}$  is the reaction

## The PDE system: the evolution of the adhesion

We consider on  $\Gamma_{\text{Cont}}$

$$\chi_t - \Delta \chi + \partial \mathbf{l}_{[0,1]}(\chi) \ni -\lambda'(\chi)(\theta_s - \theta_{\text{eq}}) - \frac{1}{2}|\mathbf{u}|^2 \quad \text{in } \Gamma_{\text{Cont}} \times (0, T)$$

$$\partial_n \chi = 0, \quad \text{on } \partial \Gamma_{\text{Cont}} \times (0, T)$$

- ▶  $\partial \mathbf{l}_{[0,1]}(\chi) \Rightarrow \chi \in [0, 1]$  (physical consistency)

$$\partial \mathbf{l}_{[0,1]}(\chi) = \begin{cases} ]-\infty, 0] & \text{if } \chi = 0 \\ 0 & \text{if } 0 < \chi < 1 \\ [0, +\infty[ & \text{if } \chi = 1 \end{cases}$$

- ▶  $\lambda$  (quadratic) function, related to the latent heat
- ▶  $\theta_s$  temperature of the glue,  $\theta_{\text{eq}}$  constant
- ▶  $-\frac{1}{2}|\mathbf{u}|^2$  source of damage due to macroscopic movements

## The PDE system: the temperature equations

- ▶ The **entropy equation** (rescaled energy balance) for  $\theta$  in  $\Omega$

$$\begin{aligned} \partial_t(\log \theta) - \operatorname{div} \mathbf{u}_t - \Delta \theta &= h \text{ in } \Omega \times (0, T), \\ \partial_n \theta &= \begin{cases} 0 & \text{on } \partial\Omega \setminus \Gamma_{\text{Cont}} \times (0, T) \\ -\chi(\theta|_{\Gamma_{\text{Cont}}} - \theta_s) & \text{on } \Gamma_{\text{Cont}} \times (0, T) \end{cases} \end{aligned}$$

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- ▶ The **entropy equation** for  $\theta_s$  on  $\Gamma_{\text{Cont}}$  is

$$\begin{aligned} \partial_t(\log \theta_s) - \lambda'(\chi)\chi_t - \Delta \theta_s &= \chi(\theta|_{\Gamma_{\text{Cont}}} - \theta_s) \quad \text{in } \Gamma_{\text{Cont}} \times (0, T) \\ \partial_n \theta_s &= 0 \quad \text{on } \partial\Gamma_{\text{Cont}} \times (0, T) \end{aligned}$$

## The complete PDE system: difficulties

$$\begin{aligned}
 & -\operatorname{div}(K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1}) = \mathbf{f} \quad \text{in } \Omega \times (0, T), \\
 & \mathbf{u} = \mathbf{0} \quad \text{on } \Gamma_{\text{Dir}} \times (0, T), \quad (K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1})\mathbf{n} = \mathbf{g} \quad \text{on } \Gamma_{\text{Neu}} \times (0, T), \\
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 & \chi_t - \Delta\chi + \partial I_{[0, 1]}(\chi) \ni -\lambda'(\chi)(\theta_s - \theta_{eq}) - \frac{1}{2}|\mathbf{u}|^2 \quad \text{in } \Gamma_{\text{Cont}} \times (0, T), \\
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 & \partial_n\theta_s = 0 \quad \text{on } \partial\Gamma_{\text{Cont}} \times (0, T), \quad +\text{Cauchy conditions}
 \end{aligned}$$

→ **singular character of the  $\theta, \theta_s$ -equations** ( $\theta$ -equation is coupled with a **third type boundary condition**)

→ we deduce directly  $\theta, \theta_s > 0$ , crucial for **thermodynamical consistency!**



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 \end{aligned}$$

→ **(quadratic) coupling** terms on the boundary

→ we need **sufficient regularity** on  $\theta$  and  $\mathbf{u}$  to control their **traces**.

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→ **non-smooth (multivalued) constraints** on  $\chi$  and  $\mathbf{u} \cdot \mathbf{n}$

## The existence theorem

**Theorem.** Given initial data

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there exist  $(\mathbf{u}, \chi, \theta, \theta_s)$  solving the **weak, variational** formulation of the **IBVP**

$$-\operatorname{div}(K\varepsilon(\mathbf{u}) + K_v\varepsilon(\mathbf{u}_t) + \theta\mathbf{1}) = \mathbf{f} \quad \text{in } \Omega \times (0, T),$$

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- we do not approximate  $\partial l_{[0,1]}(\chi)$ ,  $\partial l_{]-\infty,0]}(\mathbf{u} \cdot \mathbf{n})$  in the eq.'s for  $\mathbf{u}$  and  $\chi$

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## Uniqueness?

- ▶ **NOT expected** due to the nonlinear structure of the equations, the lack of regularity of  $\theta$  and the boundary conditions
- ▶ holds for the **approximating problem**

## Trajectories on $(0, +\infty)$

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**How the trajectories  $(\mathbf{u}(t), \chi(t), \theta(t), \theta_s(t))$  behave as  $t \rightarrow +\infty$ ?**

- ▶ need **uniform estimates** on the solutions independent of the final time  $T$
- ▶ **further requirement** on the entropy flux through  $\Gamma_c$

$$\partial_n \theta = -(\chi + c)(\theta|_{\Gamma_c} - \theta_s), \quad c > 0 \text{ on } \Gamma_c$$

$\rightsquigarrow$  residual flux even if  $\chi = 0$

(crucial to obtain a  $L^2$ -estimate for  $\theta|_{\Gamma_c} - \theta_s$ )

## Long-time a priori estimates

Due to the **dissipative character of the system**

$$|\theta|_{L^\infty(1,+\infty;H^1(\Omega))} + |\nabla\theta|_{L^2(0,+\infty;L^2(\Omega))} \leq C$$

$$|\theta_t|_{L^2(1,+\infty;L^p(\Omega))} \leq C \quad \text{for } p \leq 12/7$$

$$|\theta_s|_{L^\infty(1,+\infty;H^1(\Gamma_{\text{Cont}}))} + |\nabla\theta_s|_{L^2(0,+\infty;L^2(\Gamma_{\text{Cont}}))} \leq C$$

$$|\partial_t\theta_s|_{L^2(1,+\infty;L^q(\Gamma_{\text{Cont}}))} \leq C, \quad \text{for } q < 2$$

$$|\theta|_{\Gamma_{\text{Cont}}} - \theta_s|_{L^2(0,+\infty;L^2(\Gamma_{\text{Cont}}))} \leq C$$

$$|\chi|_{L^\infty(1,+\infty;H^2(\Gamma_{\text{Cont}}))} + |\chi_t|_{L^2(1,+\infty;H^1(\Gamma_{\text{Cont}}))} \leq C$$

$$|\mathbf{u}|_{L^\infty(0,+\infty;H^1(\Omega)^3)} + |\mathbf{u}_t|_{L^2(0,+\infty;H^1(\Omega)^3)} \leq C$$

$$|\partial_t(\log\theta)|_{L^2(0,+\infty;H^1(\Omega)')} + |\partial_t(\log\theta_s)|_{L^2(0,+\infty;H^1(\Gamma_{\text{Cont}})')} \leq C$$

⇒ the “**energy**” and the “**dissipation**” are **uniformly bounded**

⇒ the solutions trajectories **converge** in a suitable sense to some cluster points as  $t \rightarrow \infty$

## The $\omega$ -limit set

The set of the **possible cluster points**  $(\mathbf{u}_\infty, \chi_\infty, \theta_\infty, \theta_{s\infty})$  of the solutions trajectories

- ▶ is non-empty, connected and compact (w.r.t. to a suitable topology)

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$$\exists \bar{\theta}_\infty \geq 0 : \theta_\infty \equiv \bar{\theta}_\infty \quad \text{in } \Omega, \quad \theta_{s_\infty} \equiv \bar{\theta}_\infty \quad \text{in } \Gamma_{\text{Cont}}$$

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- ▶ thermomechanical equilibrium (**no dissipation**) in the limit  $t \rightarrow \infty$ .